# **Optimizing Seismic HPC in the Cloud for Performance and Cost**

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nag

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# **Numerical Algorithms Group**



## NAG

Founded 1970 Started from UK academia Offices in UK, US & Japan



# **NAG Products**

NAG Library Fortran Compiler Algorithmic Differentiation



**HPC** Managed Services

Technology evaluation & Benchmarking

Accelerator development

Code Porting / Optimization Cloud HPC Migration



Companies ARE moving HPC workloads to the Cloud

Even Oil & Gas companies



What's the best way?

(And how much will it cost?)



# This talk: Seismic HPC from the cloud

# Hypothetical Seismic workload (RTM)

- (Extremely) Brief introduction to RTM
- A few things to consider optimizing, and dials to turn

# Explore moving an RTM workload to cloud

- What cloud resources to use?
- How to pick the best resource for the workload?
- Cost-to-Solution vs Time-to-Solution





- Basically doing an ultrasound of the earth
  - Emit shock waves into the earth, they bounce back reveals subsurface image
- Reverse-Time-Migration (RTM) is taking this data, producing a volumetric image of the the subsurface
  - (-) Large amounts of input data (TB)
  - (-) Huge amounts of temporary data (PB)
  - (-) Expensive computation as well
  - (+) Each "shot" is computationally independent

# ► Adding physics/fidelity → Even more computation



# **Hypothetical Baseline – in-house RTM**

# On-prem cluster

- 480 Nodes (~1PF)
- Dual socket Intel Broadwell, 16 cores/socket, 128GB RAM
- InfiniBand 100Gb/s
- Lustre-based storage
  - 8PB storage, 256GB/s bandwidth

# Full Workload

- In-house developed RTM code
  - Isotropic acoustic model
- ~10,000 shots per campaign
  - (~350 TB raw seismic data)
- Each Shot
  - Reconstructing to 2048<sup>3</sup>
  - MPI / domain-decomposed to 4 nodes
  - 50TB snapshot data
- Full cluster, ~60 days



# **Target environment – "The Cloud"**

# "Lift & Shift"

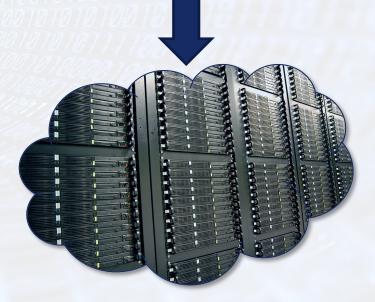
- Replicate our nodes
- Replicate our storage (and how it's used)
- Replicate our scheduler, queues, etc.

# Very difficult to match exactly

- VM instance types differ
- Interconnect may be different
- Storage totally different

# Almost NEVER cost effective







# Lift & Shift - AWS

#### Compute nodes

On Prem - Dual socket Intel Broadwell, 16/32 cores, 4GB RAM/Core (no HT)

VM Instance	vCPU	RAM	Networking	Architecture	List Price / hour	\$ / HW Core-Hour	\$/hr @ 15,360 cores
m5.24xlarge	96	384	25Gbps	Skylake/ Cascade Lake	\$4.608	\$0.096	\$1,474.560
m5n.24xlarge	96	384	100Gbps EFA	Cascade Lake	\$5.712	\$0.119	\$1,827.840
c5n.18xlarge	72	192	100Gbps EFA	Skylake	\$3.888	\$0.108	\$1,658.880
c5.18xlarge	72	144	25Gbps	Skylake	\$3.060	\$0.085	\$1,305.600
c5.24xlarge	96	192	25Gbps	Cascade Lake	\$4.080	\$0.085	\$1,305.600
c5a.24xlarge	96	192	20Gbps	Rome	\$3.696	\$0.077	\$1,182.720

#### Using on-demand Pricing

• Build your own?

Storage

- Amazon FSx for Lustre managed service various performance tiers
  - 256GB/s @ Persistent 50 5120TB @ \$0.14/GB-month -> ~\$1k/hr



# Lift & Shift - AWS

# **On-Prem**

- Compute
- 480 Nodes (~1PF)
- InfiniBand 100Gb/s
- Lustre-based storage
- 8PB storage, 256GB/s bandwidth
- ~60 days compute

# **AWS version**

- Compute
- 480 Nodes c5n.18xlarge \$1,658/hr
- EFA-based 100Gb/s
- Storage
- 8PB Lustre FSx @ 400GB/s \$1,555/hr
- ~47 days compute
- Total job cost: ~ \$3.9M



# How can we do better?

Change the application?Change the platform?

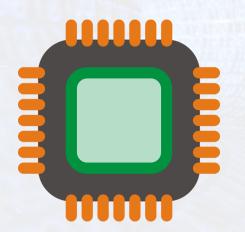




# **Change the application**

# RTM has two major sources of cost:

- Time-stepping wave equations (computational cost)
- Image condition (storage)







# **Change the application: Time-stepping**

- Time-stepping often (but not always) driven by wide stencil calculations
- Highly sensitive to vectorization and caching, but... driven by the system's memory bandwidth
- Thus common strategies for optimizing this:
  - Accelerate time-stepping with GPUs (high bandwidth devices)
  - Domain decomposition over MPI (more than one node per shot)
  - Optimize cache utilization in the stencils



# **Change the application: Image Condition**

# The image condition is usually computed in two passes:

- Forward pass: periodic snapshots made
- Reverse pass: convolved with forward pass by retrieving snapshots, accumulated into image
- The primary difficulty is dealing with snapshots, we can improve this in the following ways:
  - Store fewer snapshots, but recompute them in reverse pass (recomputation strategies)
  - Domain decompose enough that aggregate storage of all nodes can store all snapshots



# How can we do better?

# Change the application?Change the platform?







# **Change the platform**

# What all is available?

## Instance types

- Memory / CPU Speed / # cores / Storage ratios
- CPU architecture
  - What about AMD? ARM?
  - Lots of instances masquerade do you know what you're running on?
- Accelerators
- Are we "full machine" size, or some partial segment?
  - If you aren't at least full-socket, you're sharing resources

# Interconnect

• Some platforms have limited support for advanced networking (ie: IB, EFA)

Let your application be your guide

# Do a good profile of your application

Be aware of what you can profile on the cloud



# Know your bottlenecks

- CPU-bound? (Rarely, but possible) •
- Memory-bound? •
- Interconnect? Latency or Bandwidth? •
- 1/0? •



# **Addressing bottlenecks**

#### Compute-bound

- Domain-decomposition
- Accelerators
- Higher core-count nodes
- Memory bandwidth
  - Explore alternate architectures / instance sizes
  - Accelerators
  - AMD EPYC, AWS's Graviton (ARM) have higher bandwidth than Xeon

- Interconnect Bandwidth
  - Often scales with size of VM instance

## Interconnect latency

- Some clouds have HPC-focused networking – IB, EFA.
- Placement groups
- Reduce node count?
- Async communications?



# Addressing bottlenecks – I/O

# Evaluate different services & service levels

- Filesystems: NFS, Lustre, BeeGFS, NetApp, ClusterStor
- EBS volumes / Managed Disks / Persistent Disk
- Direct to Object store
- Use of local SSDs
  - I/O Optimized Nodes with many large SSDs
- Add I/O nodes to create a "private" filesystem
- Explore Asynchronous I/O options
  - Less pressure on bandwidth



# **Build a cost model**

- Too many options to keep track
- Explore options available
  - Make sure you know what you're getting!



- Understand how options interplay
  - Increase I/O bandwidth, decrease runtime
- Build a spreadsheet
  - I/O, Compute, Network
  - Bandwidths, latencies, FLOPS, etc.



Cannot focus on \$/hr for a resource

- Does including it speed up the job enough to cover the cost?
- If a job runs faster by using a more expensive resource, the total cost may be lower

# Azure example: HC vs HBv2

- HC \$3.49/hr, 44 cores
- HBv2 \$3.96/hr, 120 cores



# **RTM Workload Exploration**

- 2048x2048x2048 reconstruction volume
- 7500 Timesteps, Snapshotting every 10 steps
  - ~50TB of snapshot space / shot
- Total RAM / Shot: ~500GB
- 10,000 Shots

- Assume raw input data lives in S3
  - no extra filesystem required for it



# Options

# Storage

- Lustre FSx various performance levels 50MB/s/TiB -> 200MB/s/TiB
- EBS up to 500MB/s/Volume (Can attach multiple volumes)
- On-node NVMe/SSD/HDD

# Compute Options

- c5n 36 core "Skylake", EFA, no disk
- c5d 48 core "CascadeLake", 3.6TB NVMe
- [cmr]6g 64 core ARM "Graviton"
- c5a 96 core AMD Epyc "Rome"



Use 4x c5n.18xlarge for compute / shot

- Lustre FSx Scratch-level 6PB (120\*50)
  - 200MB/s/TiB @ \$0.14/GB-month
  - Shared across entire cluster
- EBS 1 Volume
  - 13TB for 500MB/s @ \$0.045/GB-month
- EBS 2 Volumes

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• 26TB for 1000MB/s @ \$0.045/GB-month

ft & SI

\$3.9N

\$1.97N

\$3.62

\$2.66N

# Use 6PB Lustre FSX Scratch, solve 120 shots together

- 4x c5.24xlarge \$4.08/hr (each)
  - Newer Xeon, 48 cores
- 4x c6g.16xlarge \$2.17/hr (each)
  - AWS Graviton, 128GB, 64 cores
- 1x r6g.16xlarge \$3.2256/hr (each)
  - AWS Graviton, 512GB, 64 cores



\$3.9N



# **Try different Concepts**

- Large local SSD
  - 1x i3en.24xlarge 60TB local SSD storage
  - 48 Skylake cores
  - \$10.848/hr •
- Combine Compute + Storage
  - 4x c6g.16xlarge + 1x i3en.24xlarge
- All In-Memory
  - 2x u-24tb1.metal 24TB RAM •
  - 224 Skylake cores •
  - Unknown price \$50/hr? •
- Over-decompose w/ SSD
  - 16x c5d.24xlarge ~3TB SSD •
  - 48 CascadeLake cores
  - \$4.608/hr .



\$3.9M



## **Takeaways**

Understand options available

- Know what you're getting and what you're not
- Understand your application
  - Know its bottlenecks
- Understand how options interplay
  - Increase I/O bandwidth, decrease runtime
- Build a spreadsheet cost model
  - Interplay and balance not always obvious

#### **Price-Per-Hr vs Cost-to-Solution**



# **Real world challenges**

# Integration with existing infrastructure

- Job schedulers, File Systems, etc.
- Policies, exposing infrastructure-as-code to users
- Some providers have a "cloud scheduler" that might work for you
  - AWS Batch, Azure Batch
- Availability of resources
  - Cloud really isn't infinite

## Traditional global filesystems are expensive

- Move data from cold storage to hot storage during a job return it later.
- Everything constantly changes



# **NAG Cloud HPC Migration Service**

# New service offering from NAG

- HPC Cloud migration
- Cost-to-Solution focused platform & application optimization
- Partnering with the "Big 3" providers

# https://nag.com/cloud-hpc



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